Intermittency and rough-pipe turbulence

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Recently, by analyzing the measurement data of Nikuradze [NACA Tech. Memo No. 1292 (1950)], it has been proposed [N. Goldenfeld, Phys. Rev. Lett. **96**, 044503 (2006)] that the friction factor, f, of rough-pipe flow obeys a scaling law in the turbulent regime. Here, we provide a phenomenological scaling argument to explain this law and demonstrate how intermittency modifies the scaling form, thereby relating f to the intermittency exponent, η . By statistically analyzing the measurement data of f, we infer a satisfactory estimate for $\eta \approx 0.02$, the inclusion of which is shown to improve the data-collapse curve. This provides empirical evidence for intermittency other than the direct measurement of velocity fluctuations.

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I. INTRODUCTION

A major aspect of fully developed turbulence is the existence of universal scaling laws in the so-called inertial-range scales, $l_d \ll l \ll l_0$, l_0 (l_d) being the length scale of the energetic (dissipative)-range eddies. In particular, the scaling behavior of the second-order velocity structure function under the Kolmogorov refined similarity hypothesis [1] is expressed as

$$\langle \delta v_l^2 \rangle \sim (\langle \varepsilon_l \rangle l)^{2/3} \sim l^{2/3+\eta},$$
 (1)

where $\langle \varepsilon_l \rangle$ is the average dissipation rate over a sphere of size l and η is the intermittency exponent, whose value is considered universal.

An important physical quantity in rough-pipe flow is the friction factor, f, which is related to the pressure drop across the pipe according to the Darcy-Weisbach formula (see e.g. [2]). The friction factor is a function of the Reynolds number, Re, of the flow and the relative roughness, $\frac{r}{R}$, of the pipe (r being the average size of the roughness elements and R, the radius of the pipe). f can be expressed in terms of the wall stress, τ , as $f = \frac{8\tau}{\rho V^2}$, where ρ is the density and V is the cross-sectional average of the mean-time-average velocity of the flow.

In a seminal series of experiments on rough-pipe turbulence that has remained a benchmark in the field, Nikuradze [3] elucidated how $f(\frac{r}{R}, \text{Re})$ depends on its arguments. His data were presented as six curves, which are shown in Fig. 1. The main features of these plots are as follows. Up to Re \sim 3300, the flow is still laminar and $f \sim \frac{1}{\text{Re}}$. This, of course, corroborates the exact result $f = \frac{64}{\text{Re}}$, obtained from the Navier-Stokes equation. At Re \sim 3500, the entire curve plunges to the "smooth-pipe zone" in accord with Blasius's scaling [4,5], $f \sim \text{Re}^{-1/4}$. Here the friction factor is independent of boundary roughness, due to the existence of a sufficiently thick viscous sublayer near the wall that screens the roughness elements from the turbulent flow. As Re increases, the roughness elements become progressively exposed to the turbulent flow and, at large enough Re, the flow enters the

Recently, Goldenfeld pointed out [11] that Nikuradze's data conform to the scaling form

$$f = \operatorname{Re}^{-1/4} g\left(\frac{r}{R} \operatorname{Re}^{3/4}\right),\tag{2}$$

where the scaling function g(x) has the asymptotic behavior

$$g(x) \sim \begin{cases} \text{const.}, & x \to 0 \\ x^{1/3}, & x \to \infty \end{cases}$$

and data collapse for $f \operatorname{Re}^{1/4}$ versus $\frac{r}{R} \operatorname{Re}^{3/4}$ occurs for data that lie between the Blasius and Strickler regimes. The residual deviation of data collapse from the scaling form (2), apart from uncertainties in the data, may also reflect something more fundamental [11]. Here, we address the question as to what extent (if any) intermittency corrections, which

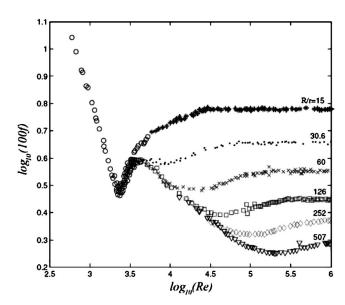


FIG. 1. Friction factor, f, of rough pipe flow versus Reynolds number, Re, for different values of relative roughness, $\frac{r}{R}$, in Ni-kuradze's experiment.

[&]quot;rough-pipe zone", where the friction factor becomes dependent only on boundary roughness in accord with Strickler's law [6], $f \sim (\frac{r}{R})^{1/3}$. These general characteristics can also be seen in other pipe [7–9] and open-channel [2,10] flow data.

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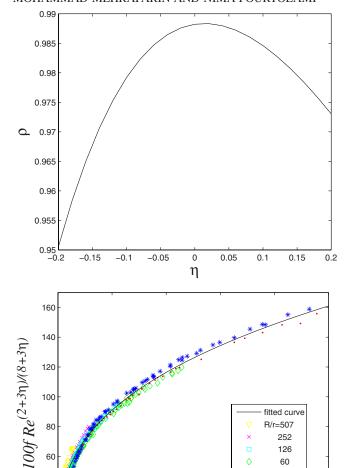


FIG. 2. (Color online) Exponential regression model. Best data correlation is obtained for the value $\eta = 0.02$ (top), resulting in the best data collapse (bottom).

 $(r/R)Re^{6/(8+3\eta)}$

20 L

100

252

60

30.6

15

500

400

have not been included in the original analysis, improve the data-collapse curve.

Although turbulent flow in a pipe is anisotropic and inhomogeneous, Kolmogorov's theory, which rests on the assumptions of isotropy and homogeneity, still applies [12–16]. Here, using Eq. (1), we provide a scaling argument to explain the scaling form (2) and demonstrate how it is modified by intermittency, thereby relating f to η . The measurement data of f can then be utilized to infer the numerical value of η , the inclusion of which is shown to improve the datacollapse curve. By statistically analyzing Nikuradze's data, we thus obtain an estimate for η (\approx 0.02) that reconciles with the available values [1,17-21]. This provides empirical evidence for intermittency other than the direct measurement of velocity fluctuations.

II. PHENOMENOLOGICAL SCALING ARGUMENT

The shear stress exerted by the flow on the wall of the pipe scales as [12,13] $\tau \sim \rho V v_r$, where $v_r = \sqrt{\langle \delta v_r^2 \rangle}$ is the velocity of eddies of length scale r, the size of roughness elements. (Such eddies have a dominant role in the momentum transfer to the wall [12,13].) Thus, the friction factor can be written as $f \sim \frac{v_r}{V}$ and hence from Eq. (1), $f \sim r^{\alpha}$ where $\alpha = \frac{1}{3} + \frac{\eta}{2}$. Let us now rescale such that $r \rightarrow lr$. Under this rescaling, we have $f \rightarrow l^{\alpha}f$. Moreover, for l > 1 (l < 1), the rescaling results in a mere amplification (deamplification) of roughness elements, without changing their geometry, thereby rendering the roughness to be exposed to the turbulent flow at lower (higher) Re. Thus, under the rescaling $r \rightarrow lr$, we expect the same flow, albeit with Re $\rightarrow l^{-\beta}$ Re, where $\beta > 0$. That is, under rescaling,

$$f\left(\frac{r}{R}, \operatorname{Re}\right) \to f\left(l\frac{r}{R}, l^{-\beta} \operatorname{Re}\right).$$

Collecting results, we therefore have

$$f\left(l\frac{r}{R}, l^{-\beta} \operatorname{Re}\right) = l^{\alpha} f\left(\frac{r}{R}, \operatorname{Re}\right).$$
 (3)

Equation (3) indicates that f is a generalized homogeneous function of its arguments in the inertial range and the behavior is self-affine. We can expound further on the exponent β , if we bear in mind that we are considering boundary layer turbulence. The turbulent transfer of momentum to the boundary wall by eddies, which predominantly takes place on length scale r (the size of dominant eddies), gives rise to an extra (eddy) viscosity near the wall. The effective viscosity in the boundary layer, therefore, scales as $\sim rv_r$ (length \times velocity), i.e., as $\sim r^{\alpha+1}$. Hence on rescaling, Re $\rightarrow l^{-\alpha-1}$ Re, i.e., $\beta = \alpha + 1 = \frac{4}{3} + \frac{\eta}{2}$ and Eq. (3) reads

$$f\left(l\frac{r}{R}, l^{-\alpha-1} \operatorname{Re}\right) = l^{\alpha} f\left(\frac{r}{R}, \operatorname{Re}\right).$$
 (4)

Goldenfeld's scaling form (2) is just a particular form of Eq. (4), which can be obtained by taking $l=Re^{1/(\alpha+1)}$ and $\eta=0$, of course. In the presence of intermittency, the scaling form thus becomes

$$f = \text{Re}^{-(2+3\eta)/(8+3\eta)} g\left(\frac{r}{R} \text{Re}^{6/(8+3\eta)}\right),$$
 (5)

where asymptotically.

$$g(x) \sim \begin{cases} \text{const.}, & x \to 0 \\ x^{1/3 + \eta/2}, & x \to \infty \end{cases}$$

Note that the Blasius and Strickler laws are, therefore, modified according to

$$f \sim \text{Re}^{-(2+3\,\eta)/(8+3\,\eta)}, \quad f \sim \left(\frac{r}{R}\right)^{1/3+\eta/2},$$

respectively. The above modified Strickler formula coincides (to lowest order) with the result obtained by Gioia et al. [12]. The modified Blasius formula, however, does not. The source of discrepancy lies in their application of the expression Re^{-3/4} for the Kolmogorov scale, which is invalid when the intermittency exponent is nonzero. The correct expression is $Re^{-6/(8+3\eta)}$, the application of which would have had

resulted in the same modified Blasius formula as given above [22].

Scaling form (5) relates the friction factor to the intermittency exponent and provides ground for the estimation of the latter via empirical data other than the direct measurement of velocity fluctuations.

III. ESTIMATION OF THE INTERMITTENCY EXPONENT

Having established Eq. (5), we proceed to infer the value of η from the measurement data of f. To this end, we plot $f \operatorname{Re}^{(2+3\eta)/(8+3\eta)}$ versus $\frac{r}{R} \operatorname{Re}^{6/(8+3\eta)}$ for different trial values of η and examine the resulting data collapse by applying regression analysis (see e.g. [23]). The best value for η is one that will result in the highest possible data correlation, i.e., the smallest possible data scatter (deviations from data-collapse curve). The data correlation coefficient, ρ , is defined by the fraction of the total variation (sum of squares) of data, y, that is explained by the regression model (fitting curve), according to

$$\rho^{2} = \frac{\sum (\hat{y} - \bar{y})^{2}}{\sum (y - \bar{y})^{2}}.$$

Here \bar{y} represents the average of data values, y, and \hat{y} are their estimated values based on the regression curve. The

closer ρ is to 1, the more correlated the data, and the better the regression. For a given regression model, we therefore examine the variation of ρ with η ; the best estimate of η is the one that yields the correlation coefficient closest to 1. Now, the polynomial regression is suitable for nonlinear data curves that show a maximum/minimum and the absence of this feature in the data-collapse curve, as shown in Fig. 2 of reference [11] (a nonzero value of η does not change this feature), renders the polynomial model irrelevant. We, therefore, resort to the exponential regression model, the result of which is presented in Fig. 2. The estimated value of η thus obtained is 0.02, which agrees with the generally expected range of values ($\approx 0.02-0.03$) reported in the literature [1,17–21]. That is to say, Nikuradze's data set [3] best conforms to $\eta \approx 0.02$ and not, in particular, to $\eta = 0$. It is rather interesting that large-scale properties, such as friction factors, can provide evidence for intermittency, which is a direct manifestation of small-scale statistics. This and similar previous observations [24] embody deep connections between spectral structure and the global properties of turbulent systems.

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